## **MotionMix: Weakly-Supervised Diffusion** for Controllable Motion Generation

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## Methodology Overview Controllable generation of 3D human motions becomes an (a) Training: Separate the diffusion steps into two distinct ranges regarding (b) Inference (two stages): important topic as the world embraces digital transformation. the data type. Clean samples are guided by an empty condition. Ground-truth Stage 1: generate rough motion guided by the conditional input. • Existing methods heavily rely on costly, annotated high-quality $s_{x}$ refers to both x-prediction and epsilon-prediction, two fundamental ٠ Stage 2: refine these rough motions to high-quality ones while the motion data. objective of diffusion models. conditional input is masked. • We propose MotionMix, a simple yet effective weakly-supervised $|\hat{\mathbf{s}}_{T-1}|$ $\hat{\mathbf{s}}_{T-2}$ $\mathbf{x}_0$ $\hat{\mathbf{s}}_{T^*}$ approach for diffusion model to utilize both noisy and unannotated Clean $c = \emptyset$ Motion motion sequences. Supervision $\hat{\mathbf{s}}_{\mathbf{x}}$ $\mathbf{x}$ $t \in [1, T^*]$ $\mathbf{s}_{\mathbf{x}}$ MotionMix MotionMix MotionMix MotionMix [Noisy Annotated Data] [Clean Unannotated Data] MotionMix c T-1 0 1 Supervision Noisy $\hat{\mathbf{s}}_{\tilde{\mathbf{x}}}$ $c \in \{\emptyset, a, w, m\}$ $\mathbf{s}_{\mathbf{\tilde{x}}}$ Motion $\mathbf{x}_T \in \mathcal{N}(0,\mathbf{I})$ $\mathbf{x}_{T-}$ $\mathbf{X}_{T^*}$ $\mathbf{x}_1$ $t \in [T^* + 1, T]$ <empty\_strir $\tilde{\mathbf{x}}$ —Stage 1: Conditional Denoising —> —Stage 2: Unconditional Denoising — **MotionMix** Evaluation Results **Text-to-Motion** Action-to-Motion Method FID ⊥ MultiModality → Accuracy ↑ $Diversity \rightarrow$ Method R Precision (top 3)<sup>↑</sup> FID↓ Multimodal Dist.↓ Diversity→ Multimodality<sup>↑</sup> $6.835^{\pm.045}$ $2.604^{\pm.040}$ Real Motion $0.053^{\pm.00}$ $0.995^{\pm.00}$ @ Real Motion $0.797^{\pm.002}$ $0.002^{\pm.000}$ $2.974^{\pm.008}$ $9.503^{\pm.065}$ $6.850^{\pm.050}$ $2.511^{\pm.023}$ rowing motion his left hand. $0.338^{\pm.015}$ $0.917^{\pm.001}$ Action2Motion $0.544^{\pm.440}$ $5.566^{\pm.027}$ $9.559^{\pm.860}$ $2.799^{\pm.072}$ ₽ MDM $0.611^{\pm.007}$ 0.338 $0.120^{\pm.000}$ 0.917 $0.955^{\pm.008}$ $6.840^{\pm.030}$ $2.530^{\pm.020}$ ACTOR 0.381<sup>±.042</sup> (†30.0%) $5.325^{\pm.026}$ (14.3%) $2.718^{\pm.019}$ ( $\downarrow 2.9\%$ ) MLD $0.077^{\pm.004}$ $0.964^{\pm.002}$ $6.831^{\pm.050}$ $2.824^{\pm.038}$ MDM (MotionMix) $0.632^{\pm.006}$ (†3.4%) $9.520^{\pm.090}$ ( $\uparrow 69.6\%$ ) $0.100^{\pm.00}$ $6.860^{\pm.050}$ MDM $0.990^{\pm.00}$ $2.520^{\pm.0}$ $0.779^{\pm.006}$ $0.031^{\pm.004}$ $2.788^{\pm.012}$ $11.080^{\pm .097}$ Setup Real Motion 0.196<sup>±.007</sup> (196%) 0.930 ±.003 (46.1% 6.836<sup>±.062</sup> (†96%) 3.043 ±.054 (1422.6%) MDM (MotionMix $0.396^{\pm.004}$ $0.497^{\pm.021}$ $9.191^{\pm.022}$ $10.847^{\pm.109}$ $1.907^{\pm.214}$ MDM Real Motio 2.790 0.988 $33.349^{\pm}$ 14.160 0.322<sup>±.020</sup> (†35.2%) 1.946<sup>±.019</sup> (†2.0%) MDM (MotionMix) $0.404^{\pm.005}$ (†2.0%) 9.068<sup>±.019</sup> (†1.3%) 10.781<sup>±.098</sup> (↓28.3%) $0.911^{\pm.003}$ Motion generation tasks and benchmarks: $23.430^{\pm 2.200}$ $31.960^{\pm.330}$ ACTOR $14.520^{\pm}$ $0.739^{\pm.004}$ $0.742^{\pm.005}$ (†0.4% $1.954^{\pm.062}$ $1.192^{\pm.073}$ (†39.0%) $2.958^{\pm.005}$ $0.730^{\pm.013}$ MLD $15.790^{\pm.079}$ $0.954^{\pm.001}$ $33.520^{\pm.140}$ $13.570^{\pm.060}$ $11.100^{\pm.143}$ MotionDiffuse $12.810^{\pm 1.460}$ $0.950^{\pm.000}$ $33.100^{\pm.290}$ $14.260^{\pm.120}$ $14.277^{\pm.094}$ ( $\downarrow 17\%$ ) $1.391^{\pm.111}$ (†90.5%) MDM $3.066^{\pm.018}$ (13.6% Text-to-Motion (T2M): HumanML3D and KIT-ML datasets MotionDiffuse (MotionMix) $10.008 \pm .072$ MDM (MotionMix) 11.400<sup>±.393</sup> (†11% 0.960<sup>±.003</sup> (±1.1% 32.806<sup>±.176</sup> (↓118% Action-to-Motion (A2M): HumanAct12 and UESTC datasets Real MDM MDM(MotionMix) MotionDiffuse MotionDiffuse (MotionMix) Music-to-Dance "a man mimics a throwing motion with his left hand." • Music-to-Dance (M2D): AIST++ dataset Method $PFC \downarrow$ Beat Align. $Dist_k \rightarrow$ $\text{Dist}_g \rightarrow$ Real Motion 1.380 0.314 9.545 7.766 MotionMix was applied to sota diffusion model of different designs: Bailando 1.754 0.23 10.58 7.72 6.14 2.2543 0.22 FACT 10.85 • MDM for T2M, A2M: x0-parameterization, classifier-free guidance. $0.224^{\pm.025}$ $1.605^{\pm .224}$ $5.549^{\pm.783}$ $4.831^{\pm.752}$ EDGEt $1.988^{\pm.120}_{(\downarrow 21.32\%)}$ $0.256^{\pm.013}$ 10.103<sup>±2.039</sup> (†95.0%) $6.595^{\pm.173}$ EDGE (MotionMix) • MotionDiffuse for T2M : epsilon-parameterization. (†13.3%) (†15.1%)

Qualitative samples from HumanML3D test set. Please view videos on our webpage

|                           |  |  |  |   |   | Ablation Sti                | laies                                     |                   |                   |  |  |  |  |   |   |  |  |  |
|---------------------------|--|--|--|---|---|-----------------------------|---|-------------------|-------------------|--|--|--|--|---|---|--|--|--|
| R Precision<br>(top 3)↑   | FID↓                                   | Multimodal<br>Dist.↓                             | $Diversity \rightarrow$  | Multimodality↑  |   |                             | R Precision                               |                   | Multimodal        |  |  |  | Method   | R Precision<br>(top 3)↑                   | FID↓                                      | Dist.↓                                 |  | Multimodality↑                                   |
| 0.797 <sup>±.002</sup> 0. |  | $2.974^{\pm.008}$                                |  | I   | Ablation on   | Method                      | (top 3)↑                                  | FID↓              | Dist.↓            | Diversity→                             | Multimodality↑   | Ablation on  | Real Motion<br>MDM   | $0.797^{\pm.002}$<br>$0.611^{\pm.007}$    | $0.002^{\pm.000}$<br>$0.544^{\pm.440}$    |  | $9.503^{\pm.065}$<br>$9.559^{\pm.860}$           | $2.799^{\pm.072}$                                |
| $0.611^{\pm .007}$ 0.     | .544 <sup>±.440</sup>                  | 5.566 <sup>±.027</sup>                           | $9.559^{\pm.860}$  | 2.799 <sup>±.072</sup>  | Noisy Ratio   | Real Motion<br>MDM          | $0.797^{\pm.002}$<br>$0.611^{\pm.007}$    |                   |                   | $9.503^{\pm.065}$<br>$9.559^{\pm.860}$ | 2.799 <sup>±.072</sup>   | Noisy Range  | 50% noisy, $T^* = T_2$<br>MDM (MotionMix) ( $T_1$ =20, $T_2$ =40)<br>MDM (MotionMix) ( $T_1$ =20, $T_2$ =60)   | $\frac{0.616^{\pm.006}}{0.632^{\pm.006}}$ | 0.451 <sup>±.033</sup>                    | 5.459 <sup>±.027</sup>                 | 9.585 <sup>±.101</sup><br>9.520 <sup>±.090</sup> | 2.585 <sup>±.076</sup><br>2.718 <sup>±.019</sup> |
| $0.598^{\pm.006}$ 0.      | $1.714^{\pm.045}$                      |  | $9.750^{\pm.123}$  |   |   | $T_1=20, T_2=60, T^*=60$    | 007                                       | + 045             | + 020             | ± 002                                  | + 074  |  | MDM (MotionMix) ( $T_1=20, T_2=80$ )   | $0.604^{\pm.004}$                         | $0.614^{\pm.060}$                         | 5.540 <sup>±.024</sup>                 | $9.554^{\pm.104}$                                | $2.768^{\pm.095}$                                |
| 0) $0.632^{\pm .006}$ 0   | $0.402^{\pm.032}$<br>$0.381^{\pm.042}$ | 5.524 <sup>±.033</sup><br>5.325 <sup>±.026</sup> | $\begin{array}{c} 9.414^{\pm.092} \\ 9.396^{\pm.094} \\ \textbf{9.520}^{\pm.090} \\ 9.242^{\pm.086} \end{array}$ | $\frac{2.935^{\pm.059}}{2.747^{\pm.070}}$ $\frac{2.718^{\pm.019}}{2.602^{\pm.057}}$ | → More clean data ≠ better,<br>more annotated data (even<br>noisy) = better | MDM (MotionMix) (50% noisy) | $\frac{0.601^{\pm.006}}{0.632^{\pm.006}}$ | $0.381^{\pm.042}$ | $5.325^{\pm.026}$ | $9.520^{\pm.090}$                      | $\frac{2.856^{\pm.074}}{2.718^{\pm.019}}$ 2.867 <sup>±.107</sup> | → MotionMix is robust<br>on different levels of<br>corrupted motions | $\begin{array}{l} {\rm 50\% \ noisy, \ T^* = T_2} \\ {\rm MDM \ (MotionMix) \ (T_1 = 10, \ T_2 = 30)} \\ {\rm MDM \ (MotionMix) \ (T_1 = 20, \ T_2 = 40)} \\ {\rm MDM \ (MotionMix) \ (T_1 = 40, \ T_2 = 60)} \\ {\rm MDM \ (MotionMix) \ (T_1 = 60, \ T_2 = 80)} \end{array}$ | $0.616^{\pm.006}$<br>$0.598^{\pm.004}$    | $\frac{0.451^{\pm.033}}{0.554^{\pm.076}}$ | $5.459^{\pm.027}$<br>$5.600^{\pm.031}$ | $9.585^{\pm.101}$<br>$9.479^{\pm.100}$           | $2.585^{\pm.076}$<br>$2.815^{\pm.094}$           |
|                           |  |  |  |   | 1   |                             |   |                   |                   |  |  |  |  |   |   |  |  |  |

EDGE for M2D : x0-parameterization with classifier-free guidance.

Method

MDM

Real Motion

50% noisy, T1=20, T2=60

MDM (MotionMix)  $(T^*=0)$ 

MDM (MotionMix)  $(T^*=20)$ 

MDM (MotionMix)  $(T^*=40)$ 

MDM (MotionMix)  $(T^*=60)$ 

MDM (MotionMix)  $(T^*=80)$ 

Ablation on

**Denoising Pivot** 

→ More clean data

does not lead to better

performance while

more annotated data

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